

SOLVABILITY AND NUMERICAL SOLUTIONS OF SYSTEMS OF NONLINEAR VOLTERRA INTEGRAL EQUATIONS OF THE FIRST KIND WITH PIECEWISE CONTINUOUS KERNELS

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The existence theorem for systems of nonlinear Volterra integral equations kernels of the first kind with piecewise continuous is proved. Such equations model evolving dynamical systems. A numerical method for solving nonlinear Volterra integral equations of the first kind with piecewise continuous kernels is proposed using midpoint quadrature rule. Also numerical method for solution of systems of linear Volterra equations of the first kind is described. The examples demonstrate efficiency of proposed algorithms. The accuracy of proposed numerical methods is $\mathcal{O}(N^{-1})$.

Keywords: Volterra integral equations; discontinuous kernel; ill-posed problem; evolving dynamical systems; quadrature; Dekker – Brent method.

1. Problem Statement and Existence Theorem. In this paper we study systems of nonlinear Volterra integral equations of the first kind with piecewise continuous kernels using our previous results [1, 2, 3, 5], where theory of linear scalar Volterra integral equations of the first kind with piecewise continuous kernels have been addressed.

Consider the following system of nonlinear Volterra equations of the first kind

$$\int_0^t K(t, s, x(s)) ds = f(t), \quad 0 \leq s \leq t \leq T, \quad f(0) = 0. \quad (1)$$

We make the following assumptions:

A) vector-function $K(t, s, x(s))$ is defined for $-\infty < x < \infty$, $0 \leq s \leq t \leq T$ and has a discontinuities of the first kind at the curves $s = \alpha_i(t)$, $i = 1, \dots, n - 1$, i. e.

$$K(t, s, x(s)) = \begin{cases} K_1(t, s)G_1(s, x(s)), & t, s \in D_1, \\ \dots & \dots \\ K_n(t, s)G_n(s, x(s)), & t, s \in D_n, \end{cases}$$

where $D_i = \{t, s \mid \alpha_{i-1}(t) < s < \alpha_i(t)\}$, $i = 1, \dots, n$, $a_0(t) = 0, a_n(t) \equiv t$, $f(t) = (f_1(t), \dots, f_m(t))'$, $x(t) = (x_1(t), \dots, x_m(t))'$, $m \times m$ matrices K_i are defined, continuous and have continuous derivatives with respect to t in the corresponding domains D_i , $f_j(t), j = 1, \dots, m$, and $\alpha_i(t)$, $i = 1, \dots, n - 1$ have continuous derivatives, $0 < \alpha'_1(0) \leq \dots \leq \alpha'_{n-1}(0) < 1$, $f_j(0) = 0, \alpha_i(0) = 0$, $0 < \alpha_1(t) < \alpha_2(t) < \dots < \alpha_{n-1}(t) < t$ for $t \in (0, T]$;

B) matrices $K_i, i = 1, \dots, n$ have continuously differentiable with respect to t continuation into compact $\{0 \leq s \leq t \leq T\}$.

For the theory of systems of linear integral equations with piecewise continuous kernels readers may refer to monograph [5]. The objective of this paper is to generalize this theory on nonlinear case and suggest algorithm for numerical solution for such systems.

It is to be noted that Volterra equations with piecewise continuous kernels are employed in energetics and in other fields for evolving dynamical systems modeling. Here readers may refer to bibliography in [2, 4].

Let us first formulate the sufficient conditions for existence and uniqueness of the solution of system (1).

Theorem 1. *Let conditions A) and B) be fulfilled for $0 \leq s \leq t \leq T$. Let Lipchitz condition $\|G_i(s, x_1(s)) - G_i(s, x_2(s)) - (x_1(s) - x_2(s))\| \leq q_i \|x_1 - x_2\|, \forall x_1, x_2 \in \mathbb{R}^n$, be also fulfilled and $q_n + \sum_{i=1}^{n-1} \alpha'_i(0) \|K_n(0, 0)^{-1}(K_i(0, 0) - K_{i+1}(0, 0))\| (1 + q_i) < 1$. Then $\exists \tau > 0$ such that system (1) has unique local solution in $\mathcal{C}_{[0, \tau]}$. Moreover, if $\min_{\tau \leq t \leq T} (t - \alpha_{n-1}(t)) = h > 0$ then such local solution can be continuously extended to the whole domain $[\tau, T]$ using combination of the method of steps and successive approximations.*

Proof of this theorem is similar to the proof of Theorem 3.2 in [2] using the Lipchitz condition.

2. Numerical Solution. In this section we construct an algorithm based on of the midpoint quadrature for numerical solution of nonlinear Volterra integral equations (1). We also included the numerical examples to demonstrate the efficiency of the proposed scheme.

For sake of clarity we first consider the scalar case. To construct a numerical solution of equation (1) on the interval $[0, T]$ introduce the mesh (not necessarily uniform)

$$0 = t_0 < t_1 < t_2 < \dots < t_N = T, \quad h = \max_{i=1, \overline{N}} (t_i - t_{i-1}) = \mathcal{O}(N^{-1}). \quad (2)$$

Following our paper [1] we search an approximate solution of equation (1) as following piecewise constant function

$$x_N(t) = \sum_{i=1}^N x_i \delta_i(t), \quad t \in (0, T], \quad \delta_i(t) = \begin{cases} 1, & \text{for } t \in \Delta_i = (t_{i-1}, t_i]; \\ 0, & \text{for } t \notin \Delta_i \end{cases} \quad (3)$$

with undetermined yet coefficients $x_i, i = \overline{1, N}$.

In order to find x_0 let us differentiate both sides of equation (1) with respect to t

$$f'(t) = \sum_{i=1}^n \left(\int_{\alpha_{i-1}(t)}^{\alpha_i(t)} \frac{\partial K_i(t, s)}{\partial t} G_i(s, x(s)) ds + \right. \\ \left. + \alpha'_i(t) K_i(t, \alpha_i(t)) G_i(\alpha_i(t), x(\alpha_i(t))) - \alpha'_{i-1}(t) K_i(t, \alpha_{i-1}(t)) G_i(\alpha_{i-1}(t), x(\alpha_{i-1}(t))) \right).$$

Then $f'(0) = \sum_{i=1}^n (\alpha'_i(0) K_i(0, 0) G_i(0, x_0) - \alpha'_{i-1}(0) K_i(0, 0) G_i(0, x_0))$. The desired coefficient x_0 is included in nonlinearly in the right hand side. We use the Van Wijngaarden

– Dekker – Brent method to find this coefficient x_0 (see e.g. [6]). Below we shall use the notation $f_k = f(t_k)$, $k = 1, \dots, N$, and v_{ij} denotes the index of mesh's segment (2) that contains the value $\alpha_i(t_j)$, i.e. $\alpha_i(t_j) \in \Delta_{v_{ij}}$. Obviously $v_{ij} < j$ for $i = \overline{0, n-1}$, $j = \overline{1, N}$. Let us now assume that the coefficients x_0, x_1, \dots, x_{k-1} of approximate solution are known. Equation (1) in the knot $t = t_k$ is $\sum_{i=1}^n \int_{\alpha_{i-1}(t_k)}^{\alpha_i(t_k)} K_i(t_k, s) G_i(s, x(s)) ds = f_k$, and it can be presented as $I_1(t_k) + I_2(t_k) + \dots + I_n(t_k) = f_k$, where

$$I_1(t_k) = \sum_{j=1}^{v_{1,k}-1} \int_{t_{j-1}}^{t_j} K_1(t_k, s) G_1(s, x(s)) ds + \int_{t_{v_{1,k}-1}}^{\alpha_1(t_k)} K_1(t_k, s) G_1(s, x(s)) ds,$$

$$I_n(t_k) = \int_{\alpha_{n-1}(t_k)}^{t_{v_{n-1,k}}} K_n(t_k, s) G_n(s, x(s)) ds + \sum_{j=v_{n-1,k}+1}^k \int_{t_{j-1}}^{t_j} K_n(t_k, s) G_n(s, x(s)) ds.$$

1. If $v_{p-1,k} \neq v_{p,k}$, $p = 2, \dots, n-1$ then

$$I_p(t_k) = \int_{\alpha_{p-1}(t_k)}^{t_{v_{p-1,k}}} K_p(t_k, s) G_p(s, x(s)) ds + \sum_{j=v_{p-1,k}+1}^{v_{p,k}-1} \int_{t_{j-1}}^{t_j} K_p(t_k, s) G_p(s, x(s)) ds + \int_{t_{v_{p,k}-1}}^{\alpha_p(t_k)} K_p(t_k, s) G_p(s, x(s)) ds.$$

2. If $v_{p-1,k} = v_{p,k}$, $p = 2, \dots, n-1$ then $I_p(t_k) = \int_{\alpha_{p-1}(t_k)}^{\alpha_p(t_k)} K_p(t_k, s) G_p(s, x(s)) ds.$

It is to be noted that the number of terms in each row of this formula depends on array v_{ij} , which can be determined based on input data: functions $\alpha_i(t)$, $i = \overline{1, n-1}$ and fixed (based on concrete N) mesh.

Each integral in the last equation can be approximated using the midpoint quadrature rule, i.e.

$$\int_{t_m}^{\alpha_p(t_k)} K_p(t_k, s) G_p(s, x(s)) ds \approx (\alpha_p(t_k) - t_m) K_p(t_k, s_k) G_p(s_k, x_N(s_k)),$$

where $m = v_{p,k} - 1$, $s_k = \frac{\alpha_p(t_k) + t_m}{2}$. Moreover, on the intervals where the desired function is determined, we select $x_N(t)$ (i.e. $t \leq t_{k-1}$). On the rest of the intervals the unknown value x_k appears in the last few terms. We determine the number of such terms using the analysis of array v_{ij} . In order to find x_k we use the Van Wijngaarden – Dekker – Brent method and proceed with computation of x_{k+1} . The accuracy of proposed method is $\varepsilon = \max_{0 \leq i \leq N} |\bar{x}(t_i) - x_N(t_i)|$, where $\bar{x}(t_i)$ and $x_N(t_i)$ are exact and approximate solution in the point t_i correspondingly. The method has order of $\mathcal{O}\left(\frac{1}{N}\right)$.

Let us now consider the numerical solution of the following system of linear integral equations

$$\int_0^t K(t, s)x(s) ds = f(t), \quad 0 \leq s \leq t \leq T, \quad f(0) = 0, \tag{4}$$

where $m \times m$ matrix kernel $K(t, s)$ on the compact $0 \leq s \leq t \leq T$ has 1st kind discontinuities on the curves $s = \alpha_i(t), i = 1, \dots, n - 1$.

An approximate solution of system (4) is searched again as a piecewise constant function $x_N(t) = (x_1^{(N)}(t), \dots, x_m^{(N)}(t))'$, where

$$x_i^{(N)}(t) = \sum_{j=1}^N x_{i,j}^{(N)} \delta_j(t), \quad t \in (0, T], \quad \delta_j(t) = \begin{cases} 1, & \text{for } t \in \Delta_j = (t_{j-1}, t_j]; \\ 0, & \text{for } t \notin \Delta_j. \end{cases} \quad (5)$$

with coefficients $x_{i,j}^{(N)}, i = \overline{1, m}, j = \overline{1, N}$.

Let us introduce the following mesh of knots

$$0 = t_0 < t_1 < t_2 < \dots < t_N = T, \quad h = \max_{i=1, N} (t_i - t_{i-1}) = \mathcal{O}(N^{-1}) \quad (6)$$

for numerical solution of system (4) on the interval $[0, T]$. Make the following notation $f_{i,k} = f_i(t_k), k = 1, \dots, N, K^{(i,p)}(t_k, s)$ is (i, p) -th entry of matrix $K(t_k, s), i = \overline{1, m}, p = \overline{1, m}$. This is the function with 1st kind discontinuities on curves $\alpha_1(t_k) < \alpha_2(t_k) < \dots < \alpha_{n-1}(t_k)$, i.e.

$$\int_0^{t_k} K^{(i,p)}(t_k, s) x_p(s) ds = \sum_{q=1}^n \int_{\alpha_{q-1}(t_k)}^{\alpha_q(t_k)} K_q^{(i,p)}(t_k, s) x_p(s) ds. \quad (7)$$

Let us differentiate both sides of equation (4) with respect to t in order to find $x_N(0)$

$$f'_i(t) = \sum_{p=1}^m \sum_{q=1}^n \left(\int_{\alpha_{q-1}(t)}^{\alpha_q(t)} \frac{\partial K_q^{(i,p)}(t, s)}{\partial t} x_p(s) ds + \right. \\ \left. + \alpha'_i(t) K_q^{(i,p)}(t, \alpha_i(t)) x_p(\alpha_i(t)) - \alpha'_{i-1}(t) K_q^{(i,p)}(t, \alpha_{i-1}(t)) x_p(\alpha_{i-1}(t)) \right).$$

Since all the components $x_p(0)$ of the desired vector $x(0)$ can be assumed constant, we gain the following system

$$f'_i(0) = \sum_{q=1}^n \left(K_q^{(i,p)}(0, 0) (\alpha'_q(0) - \alpha'_{q-1}(0)) \right) \sum_{p=1}^m x_{p,0}^{(N)}(0). \quad (8)$$

Solve the system of linear algebraic equations (8) and determine $x_{p,0}^{(N)}(0)$ for $p = \overline{1, m}$.

Let coefficients $x_{p,0}^{(N)}, x_{p,1}^{(N)}, \dots, x_{p,k-1}^{(N)}$ be known. Rewrite system (4) in the point $t = t_k$. For i th row we have

$$\sum_{p=1}^m \int_{t_{k-1}}^{t_k} K^{(i,p)}(t_k, s) x_p(s) ds = f_i(t_k) - \sum_{p=1}^m \int_{t_0}^{t_{k-1}} K^{(i,p)}(t_k, s) x_p(s) ds.$$

Taking into account (5) we obtain

$$\sum_{p=1}^m \int_{t_{k-1}}^{t_k} K^{(i,p)}(t_k, s) ds x_{p,k}^{(N)} = f_{i,k} - \sum_{p=1}^m \sum_{j=1}^{k-1} \int_{t_{j-1}}^{t_j} K^{(i,p)}(t_k, s) ds x_{p,j}^{(N)}.$$

Finally taking into account (7) we obtain the following system of linear algebraic equations

$$\sum_{p=1}^m \sum_{q=1}^n \int_{\alpha_{q-1}(t_k)}^{\alpha_q(t_k)} K_q^{(i,p)}(t_k, s) ds x_{p,k}^{(N)} = f_{i,k} - \sum_{p=1}^m \sum_{j=1}^{k-1} \sum_{q=1}^n \int_{\alpha_{q-1}(t_k)}^{\alpha_q(t_k)} K_q^{(i,p)}(t_k, s) ds x_{p,j}^{(N)}, \quad (9)$$

which is solved to determine coefficients $x_{p,k}^{(N)}$ for $p = \overline{1, m}$.

3. Numerical Examples

1.

$$\int_0^{t/8} (1+t-s) \sin x(s) ds + \int_{t/8}^{t/4} (t-1)2 \sin x(s) ds + \int_{t/4}^t (-1)(\sin^2 x(s) + 1) ds =$$

$$= -2\frac{1}{8}t + \frac{7t}{8} \cos \frac{t}{8} + (1+2t) \sin \frac{t}{8} - 2t \sin \frac{t}{4} - \frac{1}{4} \sin \frac{t}{2} + \frac{1}{4} \sin 2t, \quad t \in [0, 2].$$

The exact solution is $\bar{x}(t) = t$. Tab. 1 demonstrates errors ε for various step sizes.

Table 1

Errors for various h (example of nonlinear equation)

h	1/32	1/64	1/128	1/256	1/512	1/1024	1/2048
ε	0,345567	0,178316	0,091509	0,047107	0,023892	0,012031	0,006037

2.

$$\int_0^{t/4} \begin{pmatrix} 2+ts, & 1-ts \\ 1+t+s, & 1-ts \end{pmatrix} \cdot \begin{pmatrix} x_1(s) \\ x_2(s) \end{pmatrix} ds + \int_{t/4}^{t/2} \begin{pmatrix} 1+t+s, & t+s \\ \frac{s}{1+t}, & t+s \end{pmatrix} \cdot \begin{pmatrix} x_1(s) \\ x_2(s) \end{pmatrix} ds +$$

$$+ \int_{t/2}^t \begin{pmatrix} 1+t+s, & -1 \\ 1, & \frac{-1}{1+t} \end{pmatrix} \cdot \begin{pmatrix} x_1(s) \\ x_2(s) \end{pmatrix} ds = \begin{pmatrix} \frac{t^6}{40960} + \frac{1129t^5}{20480} + \frac{2027t^4}{24576} - \frac{55t^3}{192} \\ \frac{1}{t+1} \cdot \left(\frac{-17t^6}{20480} + \frac{4943t^5}{61440} + \frac{2107t^4}{24576} - \frac{55t^3}{192} \right) \end{pmatrix},$$

where exact solution is $\bar{x}(t) = \begin{pmatrix} t^3/8 \\ t^2 \end{pmatrix}$, $t \in [0, 2]$. Tab. 2 demonstrates errors $\varepsilon_i =$

$\max_{0 \leq j \leq N} |\bar{x}_i(t_j) - x_i^{(N)}(t_j)|$, $i = 1, 2$, where $\bar{x}_i(t_j)$ and $x_i^{(N)}(t_j)$ are corresponding exact and computed solutions in the knots t_j for various step sizes.

Table 2

Errors for various h (example of systems)

h	1/32	1/64	1/128	1/256	1/512	1/1024	1/2048
ε_1	0,054205	0,028218	0,014392	0,007267	0,003652	0,001830	0,000916
ε_2	0,127717	0,064389	0,032327	0,016196	0,008106	0,004055	0,002028

Conclusion. In this brief paper we continue our studies of Volterra integral equations of the first kind with discontinuous kernels [1–5]. We further develop the numerical methods [1] and suggest methods for solutions of systems of such linear equations and nonlinear equations. The midpoint quadrature rule is employed and the error order is $\mathcal{O}(1/N)$. The numerical method is evaluated on synthetic data and demonstrated uniform T -convergence [7] of the sequence $\{x_N(t_i)\}_{i=1}^N$ to solution $\bar{x}(t)$ with rate $\mathcal{O}(1/N)$.

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РАЗРЕШИМОСТЬ И АЛГОРИТМ ЧИСЛЕННОГО РЕШЕНИЯ СИСТЕМЫ НЕЛИНЕЙНЫХ ИНТЕГРАЛЬНЫХ УРАВНЕНИЙ ВОЛЬТЕРРА I РОДА С КУСОЧНО-НЕПРЕРЫВНЫМИ ЯДРАМИ

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Доказана теорема существования и разработан численный метод решения систем нелинейных интегральных уравнений Вольтерра первого рода с кусочно-непрерывными ядрами, возникающих в моделировании развивающихся динамических

систем. В качестве квадратурной формулы используется метод средних прямоугольников, при этом решение ищется в виде кусочно-постоянной функции. Для решения нелинейного уравнения использован комбинированный метод Дэккера и Брэнта. Приведены результаты расчетов для скалярного нелинейного уравнения и для систем линейных уравнений. Точность предложенных численных методов $O(1/N)$.

Ключевые слова: интегральные уравнения Вольтерра I рода; развивающиеся системы; разрывное ядро; нелинейные системы; численные методы; метод Дэккера и Брэнта; квадратурной формулы.

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